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## 1. Creating a workspace for catkin

**Description:** This tutorial covers how to setup a catkin workspace in which one or more catkin packages can be built.

Keywords: catkin workspace

**Tutorial Level: BEGINNER** 

Next Tutorial: Creating catkin packages (/catkin/Tutorials/CreatingPackage)

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## 2. Prerequisites

This tutorial assumes that you have installed catkin (http://www.ros.org/wiki/catkin? distro=indigo#Installing\_catkin) and sourced your environment. If you installed catkin via apt-get for ROS Inidgo, your command would look like this:

```
$ source /opt/ros/indigo/setup.bash
```

Let's create a catkin workspace (/catkin/workspaces):

```
$ mkdir -p ~/catkin_ws/src
$ cd ~/catkin_ws/src
$ catkin_init_workspace
```

Even though the workspace is empty (there are no packages in the 'src' folder, just a single CMakeLists.txt link) you can still "build" the workspace:

```
$ cd ~/catkin_ws/
$ catkin_make
```

The catkin\_make (/catkin/commands/catkin\_make) command is a convenience tool for working with catkin workspaces (/catkin/workspaces). If you look in your current directory you should now have a 'build' and 'devel' folder. Inside the 'devel' folder you can see that there are now several setup.\*sh files. Sourcing any of these files will overlay this workspace on top of your environment. To understand more about this see the general catkin documentation: catkin (/catkin). Before continuing source your new setup.\*sh file:

```
$ source devel/setup.bash
```

To make sure your workspace is properly overlayed by the setup script, make sure ROS PACKAGE PATH environment variable includes the directory you're in.

```
$ echo $ROS_PACKAGE_PATH
/home/youruser/catkin_ws/src:/opt/ros/indigo/share:/opt/ros/indigo/stacks
```

Next you should go ahead and learn how to use the workspace (/catkin/Tutorials/using a workspace).

If you are following the ROS tutorials series instead of the catkin tutorials, please continue with Creating a ROS Package (/catkin/Tutorials/CreatingPackage).

Except where

otherwise noted,

Wiki: catkin/Tutorials/create a workspace (last edited 2015-05-20 22:07:47 by DirkThomas (/DirkThomas))

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